



Autonomous
Control System

RESILIENT SCALABLE AUTONOMY



Core Architecture Attributes

From resilient navigation to resilient autonomy, LightForce is optimized for control, longevity, and operational relevance. LightForce adapts across vehicles, environments, and evolving mission demands.

Developer-First Autonomy



Purpose-built Linux OS
for your software and
custom development

Future-Ready by Design



High compute supports
evolving autonomy and
sensing technologies

GNSS-Optional Architecture



Robust navigation with
no reliance on regular
satellite positioning

Cross-Domain Flexibility



Modular hardware and
flexible I/O support
virtually all applications

Built by developers for developers, LightForce supports native workflows with an interoperable development environment compatible with C, C++, Java, Simulink, and Python. That means smarter onboarding, stronger performance, and quicker rollout across every platform you build.

SEA | LAND | AIR



SPECIFICATIONS

Mission Processor

4x Cortex-A76 @ 2.5GHz

I/O Processor

2x Cortex-M33 @ 150MHz

Embedded GPU

VideoCore VII @ 800MHz

Storage

16GB eMMC

1TB internal M.2 NVMe SSD

Power Distribution

Dual-redundant 5-32V Input

16x 5A Monitored Output

Internal Sensors

IMU

Dual Antenna RTK GNSS

Communications

Wifi

Bluetooth

2x ISM LOS

LTE

Input / Output

1x 4-lane MIPI CSI

2x 1 Gbps Ethernet

1x USB2 OTG @ 480 Mbps

16x PWM

1x I2C

1x CAN FD @ 8 Mbps

16x UART **

16x RS422/485 **

16x RS232 **

8x GPIO

8x ADC

Note: I/O further extendable with multiple units

** Software selectable



Looking for something?

LightForce is made to be customized and adapted. We offer a wide range of extension modules as well as bespoke solutions made to match your requirements. Contact us for more information!

MODULAR CAPABILITIES

Intelligence

Detect & Avoid

Smart Health Monitoring

Dynamic Path Planning

Swarming

External Sensors

Lidar

Airdata (Multi-hole Pitot)

Fibre Optic Gyroscope IMU

Visual / Thermal Camera

Navigation

Dead Reckoning

Vision-based guidance

GNSS Spoof/Jam Detection

Safety

Flight Termination (FTS)

ADS-B

Triple Redundant Voting

Remote ID

Geofencing

Advanced Control

Adaptive

Non-linear

Tethered

Communication

SATCOM

Fibre Optics

Actuators & Motors

Servo / Stepper / BLDC / +

Ground Support

Ground Control Station

SIL / HIL

MAVLink

Supported Platforms

UAV / USV / UGV

Hybrid Robotic Systems

Coordinated Swarms

Systems of Systems (SoS)

Distr. Sensor Networks